Branch Prediction

Out of order execution; advanced branch prediction

Train driver knows where he is going, but the lever puller does not. The lever puller can make an educated guess though.

The train driver could stop at the fork each time to tell the lever puller which way he is going.

OR

The lever puller makes an educated guess. If he is wrong, the train driver stops, reverses, and then continues on the right track.

5s pipeline when assume not taken

| | addi t0, | t0, | 1 | IF | ID | EX | Mem | WB | | | | | | | | | |
|---|------------------|----------------|----|--------|-----------|-------|-----|----|----|----|----|----|----|---------|---------|-------------------|-----------------|
| | addi t2, | t2, | -1 | | IF | ID | EX | М | W | | | | | | | | |
| | bne, t2, | x0, | 12 | | | IF | ID | EX | М | W | | | | | Waste 3 | | |
| | slli t0, | illi t0, t0, 1 | | | | IF | ID | EX | | | | | | every 3 | | | |
| | addi t1, | t1, | -1 | | | | | IF | ID | | | | | | (6 | iterat 6 cycle | ions es/full |
| | bne t1, x | t1, x0, x11 | | PC des | | t. | | IF | | | | | | | loop) | | |
| | addi t0, t0, 1 🗸 | | 1 | | 」, ∍ h | when | | | | IF | ID | EX | М | W | | | |
| 1 | addi t2, | ddi t2, t2, -1 | | | 1 | taken | | | | | IF | ID | EX | М | W | | |
| | bne t2, x | x0, | 12 | | | | | | | | | IF | ID | EX | М | W | |
| | slli t0, | t0, | 1 | | | | | | | | | | IF | ID | | | |
| - | | | | | | | | | | | | | | | | | |

5s pipeline when assume not taken

| addi t1, t1, -1 | IF | ID | | | | | | | | | | | |
|-----------------|-----|------|----|----|----|----|----|----|----|----|---|---|--|
| bne t1, x0, x11 | | IF | | | | | | | | | | | |
| addi t0, t0, 1 | | | IF | ID | EX | М | W | | | | | | |
| addi t2, t2, -1 | | | | IF | ID | EX | М | W | | | | | |
| bne t2, x0, 12 | not | take | n | IF | ID | EX | М | W | | | | | |
| slli t0, t0, 1 | | | | | IF | ID | EX | М | W | | | | |
| addi t1, t1, -1 | | | | | | | IF | ID | EX | М | W | | |
| bne t1, x0, x11 | | | | | | | | IF | ID | EX | М | W | |

 \odot

1-bit BPB entry

Works great for outer loop (one misprediction and then 400 correct predictions)

Works less great for inner loop:



Waste 3 cycles on 2 of

> every 3 iterations

(6 cycles/full

2-bit BPB entry

2 bits can keep track of 4 states: strong taken, weak taken, weak not taken, strong not taken

Keeps some of history (means branch prediction needs to be wrong twice instead of once before changing) – works better for the inner loop!



Branch target buffers

Cache for computing branch target address (new PC)

Potentially faster to fetch next instruction

Common in modern systems; unlike branch delay slots

Multiple ways to set this up (see Agner document)

Multiple levels

Different behavior for different types of branches/jumps





Correlated branches

if (x == 2) // branch A

x = 0;

if (y == 2) // branch B

$$y = 0;$$

...

if
$$(x != y) // branch C$$

A taken and B taken implies C not taken! → branch outcomes are often **not** independent of each other

\mathbf{O}

????

How would we design a branch predictor that can handle correlated branches?



Correlating predictors



Tournament branch predictors

Run multiple branch predictors at once

Keep track of which one is doing better (using eg 2-bit predictor!) and use that one

H&P fig. 3.4



Modern branch prediction

Agner document

H&P talking about i7:

small first-level predictor to handle cost of predicting at every cycle larger second-level predictor "as a backup"

combines two-bit, global, and loop exit predictors in tournament

The ~future~

B. Burgess, "Samsung exynos M1 processor," 2016 IEEE Hot Chips 28 Symposium (HCS), Cupertino, CA, USA, 2016, pp. 1-18, doi: 10.1109/HOTCHIPS. 2016.7936205.

<u>link</u>

Samsung M1

Branch Prediction:

- Neural Net based predictor
- Two branches/cycle
- Fetch up to 24-bytes/cycle
- 64-entry microBTB
- 4k-entry mainBTB
- 64-entry Call/Return Stack
- Indirect Predictor
- Loop Predictor

SAMSUNG

 \odot

Decoupled AddrQ



Dynamic scheduling (000 execution)

Allows executions to be rearranged at runtime (also called Out of Order, or OOO)

Advantages:

Pipeline-agnostic (code written/compiled for one uarch can work efficiently on OOO uarch)

Allows handling of dependences that can't be resolved by compiler

Allows code to execute during delay (e.g. cache miss, div, floating point)

Much more complex! But worth it in modern systems

Example

div t0, t1, t2
add t3, t0, t4
sw t3, 0(s0)
sub t4, t5, t6
mul t3, t5, t4

In-order pipeline will stall to allow div instruction to finish

Can we do better? What are the dependences?





Details of 000 execution

In-order issue

Potentially out-of-order completion

Between the time when an instruction is issued and when it completes, it is *in execution (in flight)*

Multiple instructions can be in flight at the same time, either due to multiple functional units (ALUs, FPUs, etc) or due to pipelining

How? Split up ID stage



(*we'll redraw this

picture next week)

Early 000: scoreboarding

Fascinating history of CDC 6600

Keep track of dependences between in-flight instructions and fetched instructions using dependency matrices

Issue a fetched instruction only when no dependences arise

But this is really restrictive: we can do better



By Jitze Couperus - Flickr. Supercomputer - The Beginnings, CC BY 2.0, <u>link</u>

Tomasulo's algorithm intuition

Developed by Robert Tomasulo for IBM 360/91

Minimize RAW hazards by tracking data dependences and reordering Minimize WAR and WAW hazards by *register renaming*

Limited to code within basic blocks (we'll come back to branching soon)



now the div might have enough time to write to t0 before add needs it!